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### Outline of this talk : ① (Torus) - Equivariant cohomology via GkM theory <sup>②</sup> The framework of splines-algebraic

and classical

③ Questions motivated by applied math

①Trust) Equivariant Cohomology via GKM Set-up : a suitable geometric object with a well-behaved torns action Examples: <sup>↑</sup> & <sup>X</sup> where <sup>X</sup> is · <sup>a</sup> symplectic manifold with a Hamiltonian T-action <sup>①</sup> a Smooth , complete , complex toric variety ⑧ a partial flag variety Gp with maximal torus

# T acts on <sup>X</sup> with · isolated fixed points · the boundary of each 1-orbit consists of two distinct fixed points =

· an additional condition called vivariant formality .

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· an additional condition called #equivariant formality

\* "necessary": people get this to work without

The inclusion  $2: X^{\top} \hookrightarrow X$  induces a map  $v$ sion  $v: X' \hookrightarrow X$ <br> $v^*: H^*_T(x) \longrightarrow H^*_T(x^T)$ sion  $2:\lambda^{\top}$ <br> $H^{\ast}_{\tau}(x) \longrightarrow$ often called the localization map. For some  $TCX$  this map is njective For even more special  $TCX$  we can on  $i:X' \hookrightarrow X$  induces a model  $i^*(x) \rightarrow H^*_{\tau}(x^{\tau})$ <br>led the localization map.<br>TCX this map is linjective<br>more special TCX we can<br>identify the image of  $H^*_{\tau}(x)$ <br>rantees the image  $\int$  identify the image of  $H^*_{\tau}(x)$ GKM guarantees the image more special  $T(X$  we can<br>identify the image of  $H^*(X)$ <br>rantees the Image from a particular graph



The GKM graph



For a single point, we have  
\n
$$
\mu_{\tau}^{*}(pt) = C[t_{1},...,t_{n}]
$$
\n
$$
The image of the map \n $t^{*}:H_{\tau}^{*}(x) \longrightarrow H_{\tau}^{*}(x^{T})$ \n
$$
Sds \text{ inside } C[t_{1},...,t_{n}]
$$
\n| $x^{T}|$
$$

The GKM condition The GKM condition<br>Consider the elements<br>Satisfying for each  $|x^{\mathsf{T}}|$ Consider the elements  $\overrightarrow{p} \in \mathbb{C}$  [t,,.., t,] satisfying for each edge UV GKM condition<br>
nsider the elements  $\vec{p} \in \mathbb{C}$  [t<sub>1</sub>,..., t<sub>2</sub>]<br>
tis flying for each edge uv<br>  $\boxed{p(u)-p(v)}$  is a multiple of<br>
the label  $\ell(w)$  on edge uv uv for each edge uv<br>- p(v) is a multiple of<br>Label  $\ell$  (uv) on edge uv

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It is flying for each edge uv<br>  $\boxed{p(u) - p(v)}$  is a multiple of<br>
the label  $\ell(w)$  on edge uv<br>
M Theorem: uv for each edge uv<br>- p(v) is a multiple of<br>Label  $\ell$  (uv) on edge uv The GKM con<br>Consider the el<br>satisfying for<br>Pre Label<br>EKM Theorem:<br>nese  $\frac{5}{5}$ form

GKM Theorem :

These  $\{\frac{5}{9}\}$  form the image of  $H_{f}^{*}(x)$   $\hookrightarrow H_{f}^{*}(x^{T})$ 

This identifies  $H_T^*(x)$  with a subring<br>and submodule of  $H_T^*(pt)^{|\mathbf{x}^\intercal|} = \mathbb{C}[t_1, t_2, t_3]$ using pointwise mult, add, scaling • [Equivariant formality: | H\* (x) is a free

$$
1 + \frac{1}{\sqrt{1 + \frac{1}{\sqrt
$$

(a) The framework of splines  
\nGiven any ring R (commutative, with identity)  
\nand any graph 
$$
G = (V, E)
$$
  
\nwhose edges are labeled with ideals in R  
\n $l : E \rightarrow \{$  ideals in R\}  
\nthe GKM condition defines a subring and R-submodule of R<sup>1V1</sup>

Defn	The splines on the edge-labeled
graph (G, L) with coefficients in R are	
Spl (G, L; R) = { elements $\vec{p} \in R$	
GKM	$p(u) - p(v)$ is a multiple of condition
the label l(uv) on edge uv	
for all edges uv	

<sup>①</sup> If <sup>G</sup> is the GKM graph, f(uv) is the principal ideal generated by the T-weight, and l(uv) is th<br>generated t<br>R = C [t,,  $...$ ,  $t_n$ ] =  $H^*_{T}(pt)$  then  $S_{p}$ l (G, <sup>C</sup> ; R) is the image  $|{\sf v}|$  $\iota^*$  (H $\check{\tau}$ (x)) inside  $H^*_{\tau}$ (X<sup>T</sup>) $\cong$  R<sup>'</sup>

Example :

- <sup>⑬</sup> Atlassical splines : piecewise polynomials on a polyhedral decomposition of a space , satisfying a k-differentiability constraint. Polyo <sup>=</sup> Palyo K pilyo <sup>=</sup> Pilyo i p : y=0 = py=0



$$
P_{1}|_{x=0} = P_{2}|_{x=0} \iff (P_{1}-P_{2})|_{x=0} = 0
$$



$$
p_1|_{x=0} = p_2|_{x=0} \Leftrightarrow (p_1-p_2)|_{x=0} = 0
$$
  

$$
\Leftrightarrow (p_1-p_2)(0) = 0
$$

k-clifferentiability is the ideal:  
\npolynomials on P<sub>1</sub> x=0 P<sub>2</sub> x-axis parbitored  
\n
$$
ln x
$$
 p<sub>1</sub> = p<sub>2</sub> x=0  $⇒ (p, -p_2) = 0$ 

$$
p_{1}|_{x=0} = p_{2}|_{x=0} \Leftrightarrow (p_{1}-p_{2})|_{x=0} = 0
$$
  

$$
\Leftrightarrow (p_{1}-p_{2})|_{0} = 0
$$
  

$$
\Leftrightarrow (\rho_{1}-p_{2})|_{(p_{1}-p_{2})}
$$

k-clifferentiability is the ideal:  
\npolynomials  
\n
$$
p_1
$$
 x=0  
\n $p_2$  x-axis parbitored  
\nby point x=0  
\n $p_1$  x=0  
\n $p_1$  x=0  
\n $p_2$  x=0  
\n $p_1$  x=0  
\n $p_2$  x=0  
\n $p_1$  x=0

k-clifferentiability is the ideal:  
\npolynomials  
\n
$$
p_1
$$
  
\n $p_2$   
\n $p_3$   
\n $p_4$   
\n $p_5$   
\n $p_6$   
\n $p_7$   
\n $p_8$   
\n $p_9$   
\n $p_1$   
\n $p_1$   
\n $p_2$   
\n $p_3$   
\n $p_1$   
\n<

k differentiability is the ideal -> : -> X=<sup>0</sup> X-axis partitioned polynomials o-oPi Pa in <sup>X</sup> by point <sup>X</sup> <sup>=</sup> <sup>0</sup> Plx <sup>=</sup> <sup>o</sup> = Plx <sup>=</sup> o x/(ppz) Pilx <sup>=</sup> <sup>o</sup> = Plx <sup>=</sup> <sup>o</sup> =) <sup>x</sup> = )(p, p) : pikx <sup>=</sup> <sup>0</sup> = p \* (x <sup>=</sup> <sup>0</sup> =)x\*\* )(p, p)

More generally, if F, and F<sub>2</sub> are facets with  $F_1 \cap F_2 = \{ \ell = 0 \}$ for an affine form & then

P. & P2 are piecewise K-differentiable polys



More generally, if F, and F<sub>2</sub> are facets with  $F_1 \cap F_2 = \{ \ell = 0 \}$ for an affine form 1 then P. & P2 are piecewise K-differentiable polys - Pz) where  $P_1$   $P_2$   $P_3$   $P_4$   $P_5$   $P_6$ · , Fz hen<br>  $e^{k+1}$ <br>  $e^{k+1}$ <br>  $e^{k+1}$ <br>  $e^{k+1}$ <br>  $F_2$ <br>  $F_3$ k + <sup>1</sup>

in dual graph







Example :	$R = C[x, y]$	Graph is $\mathbb{P}^1 \times \mathbb{P}^1$
or $\mathbb{P}^1 \times \mathbb{P}^1$	and labels are squared	
or $\mathbb{P}^2$	Represent splits as vertex	
do $\mathbb{P}^2$	labeled graphs	









FREE ∠⊁  $\overline{2}$  $\overline{O}$  $2x$  $\begin{array}{c} \begin{array}{c} \end{array} \end{array}$  $\overline{O}$  $\mathbf{z}$ <u>y (x-ા</u>  $(x-y)$  $\overline{O}$  $\overline{\mathsf{X}}$  $\mathbf C$  $x^2$ d  $\overline{\mathbf{c}}$  $(x-y)^2$  $\mathsf{x}$  $\mathsf{tx}$ 

## Things we can do with splines : ngs we can do with :<br>Subgraphs

· Subgraphs



· Subgraphs



· Subgraphs



- · Subgraphs
	- · Path replacement



- · Subgraphs
	- · Path replacement
	- . Change coefficients

$$
\left\{\n\begin{array}{c}\n& \mathbb{C} \left[t_1, \ldots, t_n\right] \\
& \mathbb{R} \left[t_1, \ldots, t_n\right] \\
& \mathbb{Z} \left[t_1, \ldots, t_n\right] \\
& \mathbb{Q} \text{ \textit{othern+ rings}}\n\end{array}\n\right.
$$

- · Subgraphs
	- · Path replacement
	- · Change coefficients
	- · and other algebro-combinatorial operations without obvious geometric interps



#### What does it mean topologically  $e^{k+1}$ or geometrically to use





#### What does it mean topologically geometrically to use  $K+1$ or





# Duestions<br>Can we Can we analyze spline representations?



# Duestions<br>Can we Can we analyze spline representations?

Any graph Ver analy se spline representions<br>In that<br>In the morphism that<br>In the SEM conditions<br>Inces a representation on the<br>Independent of splines automorphism that stions<br>, we analy ze spline representation<br>graph automorphism that<br>, these GKM conditions<br>, ces a representation on the<br>dule of splines | preserves GKM conditions | induces a representation on the module of splines





Spline representations:

Any action that makes combinatorial sense

Spline representations:

Any action that makes combinatorial sense

EXCHANGE HORIZONTALLY



Upper bound conjecture : For spliries on graphs dual to planar triangulations, of <u>degree</u> at most 3 opper bound conjecture:<br>For splines on graphs dual to pl<br>triangulations, of <u>degree at most 3</u><br>and <u>differentiability</u> 1 so labels<br>The conjecture is a formula for :<br>at most 3<br>1 so labels  $\boxed{l^2}$ 

The conjecture is <sup>a</sup> formula for dimension of spline space , as vector for<br>rector space

Upper bound conjecture : For splines on graphs dual to planar triangulations, of <u>degree</u> at most 3 and sound conjecture<br>Unies on graphs<br>differentiability<br>differentiability  $diams,$   $G$   $\frac{deg \cdot ee - e^{-e}}{deg \cdot ee - e^{-e}}$ 

Reaghy, it	1	2	Heages inf	1	2
# of R-models	1 + $\sum_{x \text{ non square}} 1$	1	2		
denerators	1 + $\sum_{x \text{ non square}} 1$	1			

Upper bound conjecture:		
For spluries on graphs dual to planar		
triangulations, of degree at most 3		
and differentiability I so labels [L <sup>2</sup> ]		
constant spline	for degrees 3	
If of R-module = $1 + \sum_{i=1}^{n} (*edges in F) + \sum_{v_{non}}$		
generators	face F	3

"Singular faces" are  $\frac{d}{d}$ the 4-cycle faces Singular faces are<br>the 4-cycle faces<br>with symmetry symmetry



"Singular faces" are the 4-cycle faces With symmetry  $\bullet$ E<br>R<br>S<br>S O  $\mathbf{2}$ ပ<br>ပ္က Ų  $\overline{\mathsf{x}}$ O 'o<br>D  $\overline{D}$  $\circ$ u (x-u)  $\circ$ 

### THANK YOU!